Solving Sequence Problems by Building and Sampling Edge Histograms

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Abstract. Recently, there has been a growing interest in developing evolutionary algorithms based on probabilistic modeling. In this scheme, the offspring population is generated according to the estimated probability density model of the parent instead of using recombination and mutation operators. In this paper, we have proposed probabilistic model-building genetic algorithms (PMBGAs) in permutation representation domain using edge histogram based sampling algorithms (EHBSAs). Two types of sampling algorithms, without template (EHBSA/WT) and with template (EHBSA/WT), are presented. The results were tested in the TSP and showed EHBSA/WT worked fairly well with a small population size in the test problems used. It also worked better than well-known traditional two-parent recombination operators.

1 Introduction

Genetic Algorithms (GAs) [Goldberg 89] are widely used as robust searching schemes in various real-world applications, including function optimization, optimum scheduling, and many combinatorial optimization problems. Traditional GAs start with a randomly generated population of candidate solutions (individuals). From the current population, better individuals are selected by the selection operators. The selected solutions produce new candidate solutions by applying recombination and mutation operators. Recombination mixes pieces of multiple promising sub-solutions (building blocks) and composes solutions by combining them. GAs should therefore work very well for problems that can be somehow decomposed into sub-problems. However, fixed, problem-independent recombination operators often break the building blocks or do not mix them effectively [Pelikan 00].

Recently, there has been a growing interest in developing evolutionary algorithms based on probabilistic models [Pelikan 99b], [Larranaga 02]. In this scheme, the offspring population is generated according to the
estimated probabilistic model of the parent population instead of using traditional recombination and mutation operators. The model is expected to reflect the problem structure, and as a result it is expected that this approach provides more effective mixing capability than recombination operators in traditional GAs. These algorithms are called probabilistic model-building genetic algorithms (PMBGAs) or estimation of distribution algorithms (EDAs). In a PMBGA, better individuals are selected from an initially randomly generated population like in standard GAs. Then, the probability distribution of the selected set of individuals is estimated and new individuals are generated according to this estimate, forming candidate solutions for the next generation. The process is repeated until the termination conditions are satisfied.

Many studies on PMBGs have been performed in discrete (mainly binary) domains and there are several attempts to apply PMBGAs in continuous domains. However, few studies on PMBGs in permutation domains are found. In particular, we propose an approach of PMBGs in permutation representation domains, and compare its performance with traditional recombination operators. In this approach, we develop an edge histogram matrix from the current population, where an edge is a link between two nodes in a string. We then sample nodes of a new string according to the edge histogram matrix. We will call this method the edge histogram based sampling algorithm (EHBSA). We tested the algorithm in the Traveling Salesman Problem (TSP), a typical, well-known optimization problem in permutation representation domain [Tsutsui 2002]. The results showed EHBSA worked well on the test problems used. Section 2 of this paper gives a brief overview of PMBGs. In Section 3, the two proposed EHBSAs are described. The empirical analysis is given in Section 4. Section 5 concludes the paper.

2 A Brief Overview of PMBGAs

According to [Pelikan 99b], PMBGs in binary string representation can be classified into three classes depending on the complexity of models they use; (1) no interactions, (2) pairwise interactions, and (3) multivariate interactions. In models with no interactions, variables are treated independently. Algorithms in this class work well on problems which have no interactions among variables. These algorithms include the PBIL [Baluja 94], cGA [Harik 98], and UMDA [Mhlenbein 96] algorithms. In pairwise interactions, some pairwise interactions among variables are considered. These algorithms include the MIMIC algorithm [De Bonet 97] and the algorithm using dependency trees [Baluja 97]. In models with multivariate interactions, algorithms use models that can cover multivariate interactions. Although the algorithms require increased computational time, they work well on problems which have complex interactions among variables. These algorithms include ECGA [Harik 99] and BOA [Pelikan 99a, 00].

Studies to apply PMBGs in continuous domains have also been made. These include continuous PBIL with Gaussian distribution [Sebag 98] and a real-coded variant of PBIL with iterative interval updating [Servet 97]. In [Gallagher 99], PBIL is extended by using a finite adaptive Gaussian mixture model density estimator. The UMDA and MIMIC were introduced in continuous domain. All of the above algorithms do not include any interactions among the variables. In EGNA [Larranaga 99], a Gaussian network learns to estimate a multivariate Gaussian distribution of the parent population. In [Bosman 99], two density estimation models, i.e., the normal distribution, and the histogram distribution are discussed. These models are intended to cover multivariate interaction among variables. In [Bosman 00a], it is reported that the normal distribution models have shown good performance. In [Bosman 00b], a normal mixture model combined with a clustering technique is introduced to deal with non-linear interactions. In [Tsutsui 01a, b], an evolutionary algorithm using marginal histogram models in continuous domain was proposed.
A study on PMBGAs in permutation representation domain is found in [Robles 02]. In it, PMBGAs are applied to solving TSP using two approaches. One is to use discrete PMBGAs and the other is to use continuous PMBGAs. In applying discrete PMBGAs, several different Bayesian network structures are compared and the All Time Modification (ATM) method was used to ensure that all the generated individuals were correct. In applying continuous PMBGAs, the correct tour is obtained by sorting the vectors of real numbers. PMBGAs are also applied to solve job shop scheduling problems and graph matching problems [Larranaga 02].

3 Edge Histogram Based Sampling Algorithm (EHBSA)

This section describes how the edge histogram based sampling algorithm (EHBSA) can be used to (1) model promising solutions and (2) generate new solutions by simulating the learned model.

3.1 The Basic Description of the Algorithm

An edge is a link or connection between two nodes and can be used to encode important information about the permutation. Some crossover operators, such as Edge Recombination (ER) [Whitley 89] and enhanced ER (eER) [Starkweather, 91] which are used in traditional two-parent recombination, use the edge distribution only in the two parents string. The basic idea of the edge histogram based sampling algorithm (EHBSA) is to use the edge histogram of the whole population in generating new strings.

The algorithm starts by generating a random permutation for each individual population of candidate solutions. Promising solutions are then selected using any popular selection scheme. An edge histogram matrix (EHM) for the selected solutions is constructed and new solutions are generated by sampling according to the edge histogram matrix. New solutions replace some of the old ones and the process is repeated until the termination criteria are met. This algorithm can be seen as a permutation version of the algorithm that uses marginal histogram models proposed in [Tsutsui 01a, b].

3.2 Developing Edge Histogram Matrix

Let the string of the kth individual in population $P(t)$ at generation $t$ be represented as $s'_k = (\pi'_0, \pi'_1, ..., \pi'_{L-1})$. $(\pi'_0, \pi'_1, ..., \pi'_{L-1})$ are the permutation of $(0, 1, ..., L-1)$, where $L$ is the length of the permutation. The edge histogram matrix $EHM'(e'_{i,j}) (i,j =0,1, ..., L-1)$ of population $P(t)$ is symmetrical and consists of $L^2$ elements as follows:

$$e'_{i,j} = \begin{cases} \sum_{k=1}^{N} (\delta_{i,j}(s'_k) + \delta_{j,i}(s'_k)) + \varepsilon & \text{if } i \neq j \\ 0 & \text{if } i = j \end{cases}$$

where $N$ is the population size, $\delta_{i,j}(s'_k)$ is a delta function defined as

$$\delta_{i,j}(s'_k) = \begin{cases} 1 & \text{if } \exists h \in [0,1,\cdots,L-1] \land \pi'_i(h) = i \land \pi'_j((h+1)\mod L) = j \\ 0 & \text{otherwise} \end{cases}$$

and $\varepsilon (\varepsilon > 0)$ is a bias to control pressure in sampling nodes just like that used for adjusting the selection pres-
sure in the proportional selection in GAs. The average number of edges of element \( e_{t,ij} \) in \( EHM_t \) is \( 2LN/(L^2-L) = 2N/(L-1) \). Values \( e_{t,ij} \) will be later be used in a variant of proportionate selection, and the value of \( \varepsilon \) thus influences selection pressure toward edges. To achieve comparable selection pressure for all problems and parameter settings, \( \varepsilon \) should be proportional to the expected value of \( e_{t,ij} \). Therefore,

\[
\varepsilon = \frac{2N}{L-1} B_{\text{ratio}}
\]

where \( B_{\text{ratio}} \) (\( B_{\text{ratio}} > 0 \)), the bias ratio, is a constant related to selection pressure. A smaller value of \( B_{\text{ratio}} \) reflects the real distribution of edges in sampling of nodes and a bigger value of \( B_{\text{ratio}} \) will give a kind of perturbation in the sampling (see Section 3.3). An example of \( EHM_t \) is shown in Fig. 1.

![Symmetric edge histogram matrix](image)

Fig. 1. An example of symmetric edge histogram matrix for \( N = 5, L = 5, B_{\text{ratio}} = 0.04 \)

Although we defined a symmetric \( EHM_t \), i.e., \( e_{i,j} = e_{j,i} \), which is applicable to problems such as a symmetric TSP, we can also define an asymmetric \( EHM_t \) for problems such as an asymmetric TSP or scheduling problems with permutation representation. An asymmetric \( EHM_t \) can be easily defined by a equation similar to Eq. 1.

### 3.3 Sampling Algorithms

In this subsection, we describe how to sample a new string from the edge histogram matrix \( EHM_t \). We propose two types of sampling algorithms; one is an edge histogram based sampling algorithm without template (EHBSA/WO), and the other an edge histogram based sampling algorithm with template (EHBSA/WT).

#### 3.3.1 Edge histogram based sampling algorithm without template (EHBSA/WO)

In EHBSA/WO, a new individual permutation \( c[] \) is generated based on the \( EHM_t \). First, we randomly select the initial node for position 0, and set it to \( c[0] \). Then, the next node for position 1 (\( c[1] \)) is obtained by sampling an edge which contains node \( c[0] \). This sampling is performed by roulette wheel proportional sampling, based on the edge histograms \( e_{t,ij} \) (\( j = 0, 1, ..., L-1, j \neq c[0] \)) in \( EHM_t \). This sampling is repeated until all nodes are obtained. In this sampling, edges that are once sampled are removed from \( EHM_t \), i.e. their elements in \( EHM_t \) are set to 0, so that no duplicated nodes are obtained. Fig. 2 shows the schematic description of the edge histogram based sampling algorithm without template (EHBSA/WO).
Here, note that the EHBSA/WO described above is only applicable to problems where the absolute position of each node in a string has no meaning, such as in the TSP. Slight modifications are required to apply it to problems where the absolute position of each node in a string has meaning, such as in scheduling problems. This sampling algorithm is similar in part to the sampling in Ant Colony Optimization [Dorigo 96].

3.3.2 Edge histogram based sampling algorithm with template (EHBSA/WT)

EHM described in Section 3.2 does not consider interactions between different edges. It has no explicit graphical structure. EHBSA/WT is intended to make up for this disadvantage by using a template in sampling a new string. In EHBSA/WT, a template individual is chosen from \( P(t) \) (normally, randomly). A new individual is generated by sampling a number of nodes in positions (loci) within the template string while nodes in other positions remain unchanged.

The problem here is how to determine the positions of sampled nodes. The positions should not be fixed loci and the number of positions should not be a fixed value. If we were to fix them, the search could only be performed in local search mode. In this research we propose a method that borrows the basic idea from the \( n \) cut-point crossover in traditional GAs. The \( n \) \( (n > 1) \) cut points are applied to the template randomly. When \( n \) cut points are obtained for the template, the template should be divided into \( n \) segments. Then, we choose one segment randomly and sample nodes for the segment. Nodes in other \( n-1 \) segments remain unchanged. We denote this sampling algorithm by EHBSA/WT/\( n \). Since \( n \) cut points take random values, a segment generated by these cut points is random in position and length (see Subsection 4.3). Fig. 3 shows an example of EHBSA/WT/3 where 3 cut points are applied. In this example, three segments, segment1, segment2 and segment3 are generated by cut points cut[0], cut[1] and cut[2], and segment1 is chosen for sampling nodes. Nodes of the new string in segment0 and segment2 (before cut[1] and after cut[2]) are the same as the nodes of the template. New nodes are sampled for only segment1 (from cut[1] up to, but not including, cut[2]) based on the EHM using a similar algorithm to that in EHBSA/WO.
4 Empirical Study

4.1 Experimental Methodology

4.1.1 Evolutionary models

Here, we describe evolutionary models for EHBSA/WT, EHBSA/WO, and two-parent recombination operators, respectively. All these models are basically the same as steady state models.

(1) Evolutionary model for EHBSA/WT

Let the population size be $N$, and let it, at time $t$, be represented by $P(t)$. The population $P(t+1)$ is produced as follows (Fig. 5):
1. Edge histogram matrix $EHM_t$ described in Subsection 3.2 is developed from $P(t)$.
2. A template individual $T[]$ is selected from $P(t)$ randomly.
3. EHBSA/WT described in Subsection 3.3.2 is performed using $EHM_t$ and $T[]$, and generate a new individual $c[]$.
4. The new $c[]$ individual is evaluated.
5. If $c[]$ is better than $T[]$, then $T[]$ is replaced with $c[]$, otherwise $T[]$ remains, forming $P(t+1)$.

![Evolutionary model for EHBSA/WT](image)

**Fig. 5.** Evolutionary model for EHBSA/WT

(2) **Evolutionary model for EHBSA/WO**

The evolutionary model for EHBSA/WO is basically the same as the model for EHBSA/WT except EHBSA/WO does not use a template $T[]$. The new string $c[]$ compares randomly selected individual $i[]$ in $P(t)$, and if $c[]$ is better than $i[]$, $i[]$ is replaced with $c[]$.

(3) **Evolutionary model for two-parent recombination operators**

To compare the performance of the proposed methods with the performance of traditional two-parent recombination operators, we designed an evolutionary model for two-parent recombination operators. For fair comparison, we design it as similar as possible to that of the EHBSA. We generate only one child from two parents. Using one child from two parents is already proposed for designing the GENITOR algorithm by Whitley et al. [Whitley 89]. In our generational model, two parents are selected from $P(t)$ randomly. No bias is used in this selection. Then we apply a recombination operator to produce one child. This child is compared with its parents. If the child is better than the worst parent, then the parent is replaced with the child.
4.1.2 Test suite and performance measures

We tested the algorithm in the Traveling Salesman Problem (TSP), a typical, well-known optimization problem in permutation representation domain. The following well-known data files have been used in this empirical study: 24 cities gr24, 48 cities gr48, and 76 cities pr76. The gr24 and gr48 are used in the study of TSP with EDA in [Robles 02]. We compared EHBSA with popular order-based recombination operators, namely, the original order crossover OX [Oliver 87], the enhanced edge recombination operator eER [Starkweather 91], and the partially mapped crossover [Goldberg 89]. We also tried to compare EHBSA with results in [Robles 02] on gr24 and gr48.

Ten runs were performed. Each run continued until the optimum tour was found, the population was converged, or evaluations reached \( E_{\text{max}} \) Values of \( E_{\text{max}} \) were 50000, 500000, and 1000000 for gr24, gr48, and pr76, respectively. Population sizes of 60, 120, 240 were used for EHBSA, and 60, 120, 240, 480,960 for other operators, respectively. As to the bias ratio \( B_{\text{ratio}} \) in Eq. 3, \( B_{\text{ratio}} \) values of 0.03, 0.015, and 0.005 were used for gr24, gr48, and pr76, respectively.

We evaluated the algorithms by measuring their \#OPT (number of runs in which the algorithm succeeded in finding the optimum tour), ANE (average number of evaluations to find the global optimum in those runs where it did find the optimum), and Aver (average length of best solution in each run). Here, a lower value of ANE means a more effective search capability of an algorithm.

4.1.3 Blind search

In solving the TSP using GAs, mutation operators play an important role. Several types of mutation operators are proposed. Also, it is well known that combining GAs with local optimization methods or heuristics greatly improves the performance of the algorithms. Many kinds of heuristics for TSP are proposed [Johnson 02]. For example, in [Ulder 90], Ulder et al. combined GAs with 2-opt heuristics and the algorithm showed greatly improved performance. In [Nagata 97], Nagata et al. proposed a high-power crossover operator for TSP which includes a kind of heuristics in the operator.

In this experiment, we use no mutation and no heuristic to see the pure effect of applying the proposed algorithms. Thus, the algorithm is a blind search.

4.2 Empirical Analysis of Results

Results in gr24 are shown in Table 1. EHBSA/WO found the optimum tour 7, 9, and 6 times with \( N = 60, 120, \) and 240, respectively. On the other hand, EHBSA/WT/\( n \) found the optimum tour 10 times for all experiments. The ANEs of EHBSA/WT/2 and EHBSA/WT/3 were 9141, and 9523, respectively, showing good performance. Thus, we can see the performance of EHBSA/WT is much better than EHBSA/WO. In the other operators, eER showed good performance. The eER with \( N = 240, 480, \) and 960 found the optimum tour 10 times and the ANE for \( N = 240 \) was 13394, which is a little larger than EHBSA/WT/\( n \) with \( N = 60 \). OX showed worse performance than eER although PMX showed the worst performance. Comparing the performance of EHBSA/WT with other operators, EHBSA/WT is slightly better than eER and is much better than OX and PMX. One big difference between EHBSA/WT and eER is that EHBSA/WT requires a smaller population size to work than eER. To compare EHBSA with results in [Robles 02] we see the results with discrete representation (here referred to as discrete EDA). In [Robles 02], it is shown that the discrete EDA without local
search does not find the optimum tour.

### Table 1. Results of gr24

<table>
<thead>
<tr>
<th>Model</th>
<th>Population Size N</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>#OPT ANE Aver</td>
</tr>
<tr>
<td>EHBSA/WO</td>
<td>7 16328 1281 9 23637 1273 6 44853 1280</td>
</tr>
<tr>
<td>EHBSA/WT/2</td>
<td>10 9141 1272 10 17978 1272 10 35604 1272</td>
</tr>
<tr>
<td>EHBSA/WT/3</td>
<td>10 9523 1272 10 18251 1272 10 32956 1272</td>
</tr>
<tr>
<td>EHBSA/WT/4</td>
<td>10 10677 1272 10 17652 1272 10 33606 1272</td>
</tr>
<tr>
<td>EHBSA/WT/5</td>
<td>10 11170 1272 10 20489 1272 10 36078 1272</td>
</tr>
<tr>
<td>OX</td>
<td>0 - 1345 1 22449 1303 4 34140 1303 0 - 1484</td>
</tr>
<tr>
<td>eER</td>
<td>1 4738 1299 7 6237 1276 10 13394 1272 10 23785 1272 10 42767 1272</td>
</tr>
<tr>
<td>PMX</td>
<td>0 - 1492 0 4141 1341 10 49442 1316 0 - 1572</td>
</tr>
</tbody>
</table>

Other PMBGA*  #OPT=0, ANE is not available, best length = 1328 with MIMIC, best Aver = 1439 with EBNA

Optimum: 1272
$E_{\text{max}} = 50000, B_{\text{ratio}} = 0.03$

* Best data without heuristic using discrete EDA in [Robles 02]. Maximum number of evaluations is 50000.

Results in gr48 are shown in Table 2. EHBSA/WO could not find the optimum tour in gr48. On the other hand, EHBSA/WT/n again found the optimum tour 10 times for all experiments except EHBSA/WT/4 and EHBSA/WT/2 with N = 60. The ANEs for EHBSA/WT/3 and EHBSA/WT/5 were 85387 and 89799, respectively, showing good performance. Thus, we can see again the performance of EHBSA/WT is much better than EHBSA/WO. In the other operators, eER showed weaker performance than EHBSA/WT/n in gr48, but better performance than OX. The best #OPT of eER is 5 with N = 960 and the ANE of this case is 166286, much larger than EHBSA/WT/n. PMX could not find the optimum tour. Comparing the performance of EHBSA/WT with discrete EDA in [Robles 02] is impossible because both termination conditions are different in gr48.

### Table 2. Results of gr48

<table>
<thead>
<tr>
<th>Model</th>
<th>Population Size N</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>#OPT ANE Aver</td>
</tr>
<tr>
<td>EHBSA/WO</td>
<td>0 - 5212 0 - 5316 0 - 5773</td>
</tr>
<tr>
<td>EHBSA/WT/2</td>
<td>6 102691 5053 10 174123 5046 10 299391 5046</td>
</tr>
<tr>
<td>EHBSA/WT/3</td>
<td>10 85387 5046 10 134597 5046 10 240391 5046</td>
</tr>
<tr>
<td>EHBSA/WT/4</td>
<td>9 82701 5047 10 126444 5046 10 237260 5046</td>
</tr>
<tr>
<td>EHBSA/WT/5</td>
<td>10 89799 5046 10 157041 5046 10 257486 5046</td>
</tr>
<tr>
<td>OX</td>
<td>0 - 5527 0 - 5268 0 - 5200 1 162154 5099 2 287852 5082</td>
</tr>
<tr>
<td>eER</td>
<td>0 - 5653 0 - 5233 0 - 5098 2 95075 5072 5 166286 5058</td>
</tr>
<tr>
<td>PMX</td>
<td>0 - 8285 0 - 7374 0 - 6859 0 - 6116 0 - 5860</td>
</tr>
</tbody>
</table>

Other PMBGA*  #OPT=0, ANE is not available, best length = 6104 with MIMIC, best Aver = 6717 with MIMIC

Optimum: 5046
$E_{\text{max}} = 500000, B_{\text{ratio}} = 0.015$

* Best data without heuristic using discrete EDA in [Robles 02]. Maximum number of evaluations was set to 50000
Results in pr76 are shown in Table 3. EHBSA/WO could not find the optimum tour in pr76. On the other hand, EHBSA/WT/n found the optimum tour several times. With \( N = 60 \), EHBSA/WT/2, 3, 4, and 5 found the optimum tour 4, 4, 9, and 10 times, respectively. With \( N = 120 \), EHBSA/WT/2, 3, 4, and 5 found the optimum tour 9, 9, 9, and 10 times, respectively, showing the best performance. Thus, we can see the performance of EHBSA/WT is much better than the performance of EHBSA/WO in this experiment, too. In the other operators, eER found the optimum tour only 1 time with \( N = 480 \) and 3 times with \( N = 960 \), showing worse performance than EHBSA/WT. OX and PMX could not find the optimum tour.

<table>
<thead>
<tr>
<th>Model</th>
<th>Population Size N</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>60</td>
</tr>
<tr>
<td></td>
<td>ANE</td>
</tr>
<tr>
<td>EHBSA/WO</td>
<td>0</td>
</tr>
<tr>
<td>EHBSA/WT/2</td>
<td>4</td>
</tr>
<tr>
<td>EHBSA/WT/3</td>
<td>4</td>
</tr>
<tr>
<td>EHBSA/WT/4</td>
<td>9</td>
</tr>
<tr>
<td>EHBSA/WT/5</td>
<td>10</td>
</tr>
<tr>
<td>OX</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>eER</td>
<td>0</td>
</tr>
<tr>
<td>PMX</td>
<td>0</td>
</tr>
<tr>
<td>Other PMBGA</td>
<td>not available</td>
</tr>
</tbody>
</table>

Optimum: 108159

\( E_{\max} = 1000000, B_{\text{rate}} = 0.005 \)

### 4.3 Discussion

From the results described in Sub-section 4.2, we can see that EHBSA/WT/n worked much better than EHBSA/WO in the test problems used. It also worked better than popular traditional two-parent recombination operators. In EHBSA/WT/n, sampling is performed only in a randomly generated segment by \( n \) cut points \( \text{cut}[l] (l = 0, 1, \ldots, n-1) \). Now let us obtain the distribution of the length of a segment in EHBSA/WT/n.

The string length \( L \) and each cut point are integer values. But for simplicity, here we assume \( L \) and each cut point \( \text{cut}[l] (l = 0, 1, \ldots, n-1) \) to take continuous values. There is an edge between the last node and the first node in a string. Thus, we represent a string as a continuous circle of length \( L \) as shown in Fig. 6. Then, the length of a segment can be calculated as a continuous value. Without loss of generality, we fix the cut point \( \text{cut}[0] \) as the origin, and consider the segment between cut point \( \text{cut}[0] \) and cut point \( \text{cut}[1] \) as a typical random segment, where cut point \( \text{cut}[1] \) is defined as the nearest cut point in clockwise rotation to cut point \( \text{cut}[0] \) (see Fig. 4). Let \( F(x) \) and \( f(x) \) be the probability distribution function and the probability density function of the length of the segment described above, respectively. Let \( F'(x) \) be the probability that all cut points \( \text{cut}[l] (l = 1, 2, \ldots, n-1) \), excluding \( \text{cut}[0] \), are greater than \( x \). The probability that a cut point \( \text{cut}[l] (l \neq 0) \) is greater than \( x \) is \( 1-x/L \). So, \( F'(x) \) is obtained as
Then, \( F(x) \) can be obtained from \( F'(x) \) as

\[
F(x) = 1 - F'(x) = 1 - \left(1 - \frac{x}{L}\right)^{n-1}.
\] (5)

The density function \( f(x) \) is obtained from \( F(x) \) as

\[
f(x) = \frac{d}{dx} F(x) = \frac{(n-1)}{L} \left(1 - \frac{x}{L}\right)^{n-2}.
\] (6)

The average of \( x \) is obtained as

\[
\bar{x} = \int_0^L x \cdot f(x) dx = \frac{L}{n}.
\] (6)

Fig. 6. Calculation of length a segment formed by \( n \) cut points

Fig. 7 shows the probability density function \( f(x) \). For \( n = 2 \), \( f(x) \) is uniformly distributed on \([0, L] \). Thus, the length of a segment to be sampled in EHBSA/WT/2 is uniformly distributed on \([0, L] \). When the length of the segment is small, the EHBSA/WT/2 samples a small number of nodes, performing a kind of local search improvement over the template individual. On the other hand, when the length is large, the EHBSA/WT/2 samples a large number of nodes, performing a kind of global search improvement over the template individual or produces a new string. Due to the uniform distribution of segment lengths on \([0, L] \), EHBSA/WT/2 balances global and local improvements.
For $n > 2$, short segments are more likely to occur. As a result, a smaller number of $n$ work well with problems with smaller numbers of cities, and a larger number of $n$ work well with problems with larger numbers of cities; i.e., gr24: $n = 2$, gr48: $n = 3$, and pr76: $n = 5$.

In EHBSAs, the population size appears to be a crucial parameter as with traditional GAs. But one interesting feature of EHBSA/WT/$n$ is that it requires smaller population size than traditional two-parent recombination operators. This may be an important property of EHBSA/WT/$n$. In our experiments, we used a blind search. When we combine EHBSA/WT/$n$ with some heuristics, we expect it to work well with a smaller population size.

![Figure 7. Probability density function $f(x)$](image)

5 Conclusions

In this paper, we have proposed probabilistic model-building genetic algorithms (PMBGAs) in permutation representation domain using the Traveling Salesman Problem (TSP), a typical, well-known optimization problem in permutation representation domain and compare its performance with traditional recombination operators. In this approach, we developed an edge histogram model from the current population. Two types of sampling algorithms, EHBSA/wo and EHBSA/WT, were presented. The results showed EHBSA/WT worked fairly well with a smaller size of population on the test problems used. It also worked better than well-known traditional two parent recombination operators.

There are many opportunities for further research related to the proposed algorithms. The effect of the number of cut points of the template $n$, the parameter values of $B_{ratio}$, and the size of population $N$ on the performance of the algorithm must be further investigated. We experimented with EHBSAs using a blind search to test the pure mixing capability of the proposed algorithms. But we must test the algorithms with appropriate heuristics in problems with large numbers of cities. Analyzing the time complexity of the algorithm, and applying EHBSAs to other permutation problems, such as job-shop scheduling problems, also remain for future work.
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